

Fig. 2A

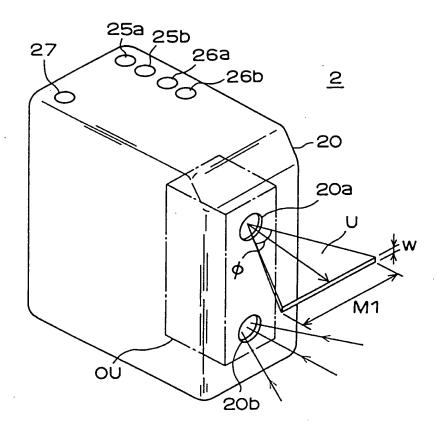
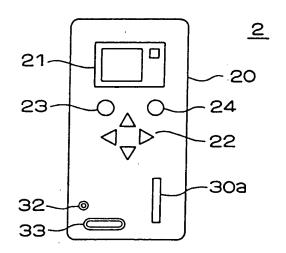


Fig. 2B



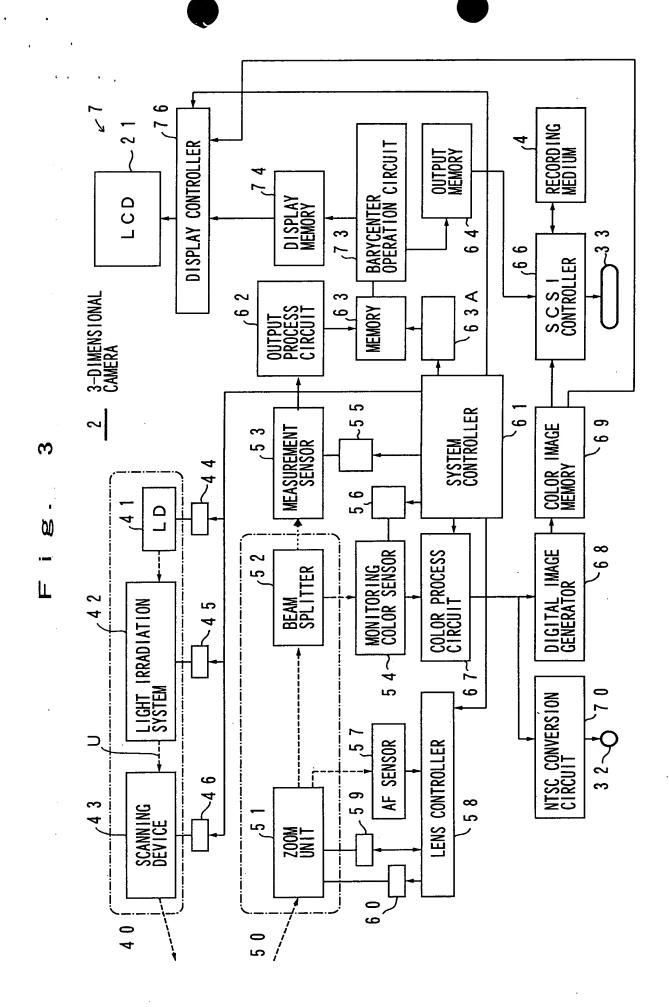


Fig. 4A

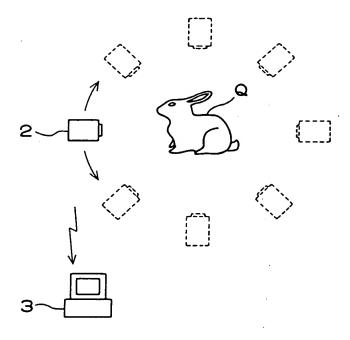
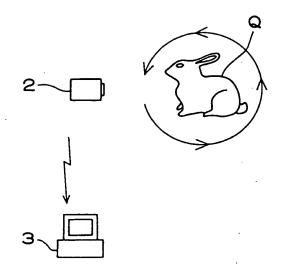
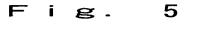


Fig. 4B





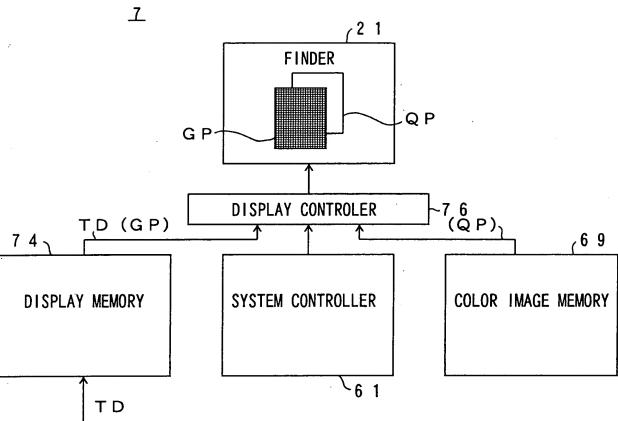


Fig. 6A

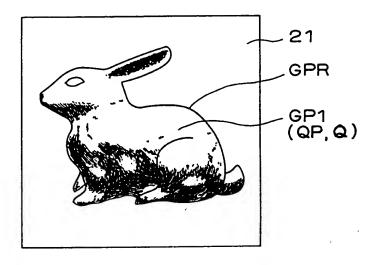
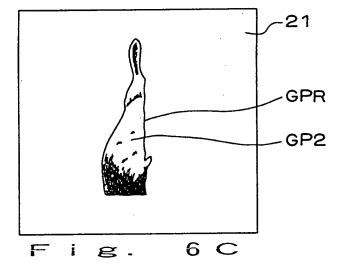
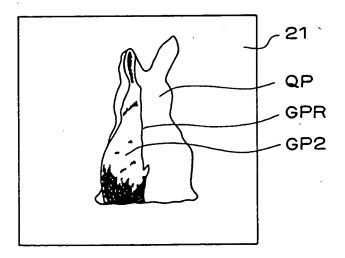
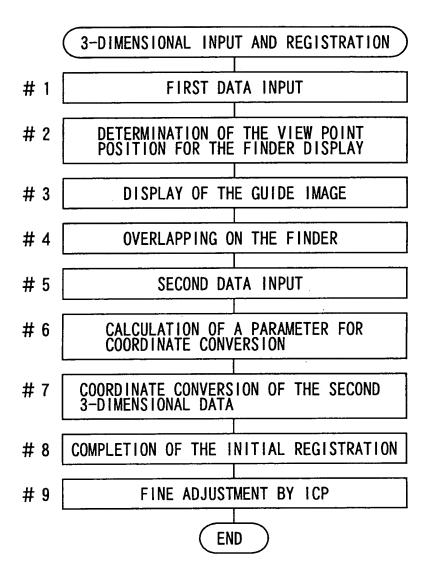
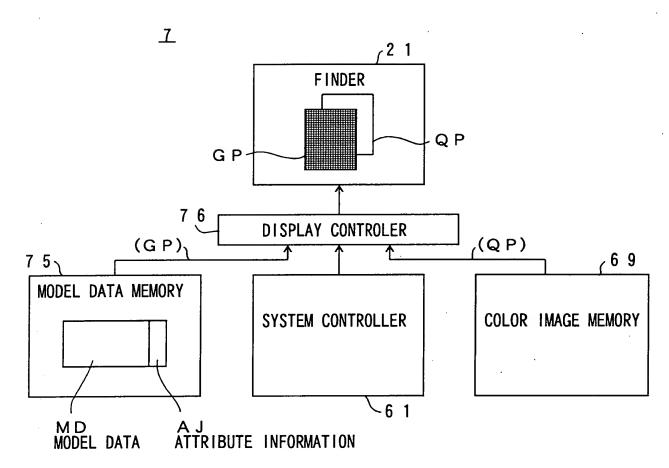


Fig. 6B









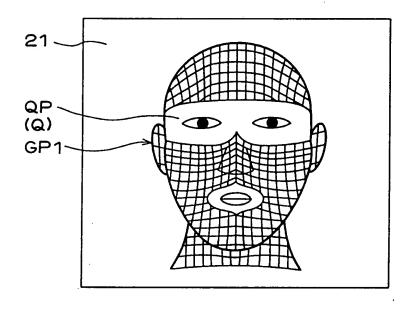
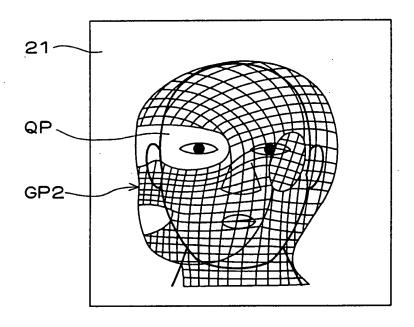
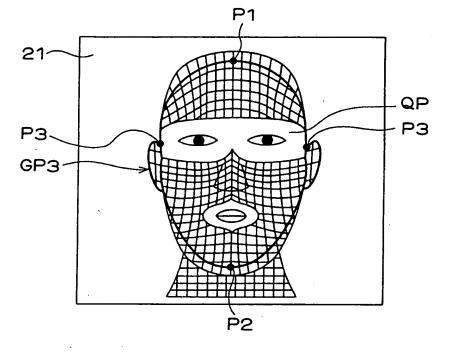


Fig. 9B



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	3-DIMENSIONAL INPUT AND REGISTRATION
# 1	DISPLAY OF THE MONITOR IMAGE
# 2	DISPLAY OF THE GUIDE IMAGE
# 3	OVERLAPPING ON THE FINDER
# 4	DETERMINATION OF THE VIEW POINT POSITION FOR THE FINDER DISPLAY
# 5	FIRST DATA INPUT
# 6	DISPLAY OF THE NEXT GUIDE IMAGE
# 7	OVERLAPPING ON THE FINDER
# 8	SECOND DATA INPUT
# 9	CALCULATION OF A PARAMETER FOR COORDINATE CONVERSION
#10	COORDINATE CONVERSION OF THE SECOND 3-DIMENSIONAL DATA
#11	COMPLETION OF THE INITIAL REGISTRATION
#12	FINE ADJUSTMENT BY ICP
	END



DAGUETER OUTEDS

